

Excited States and Nonadiabatic Dynamics
CyberTraining School/Workshop 2023

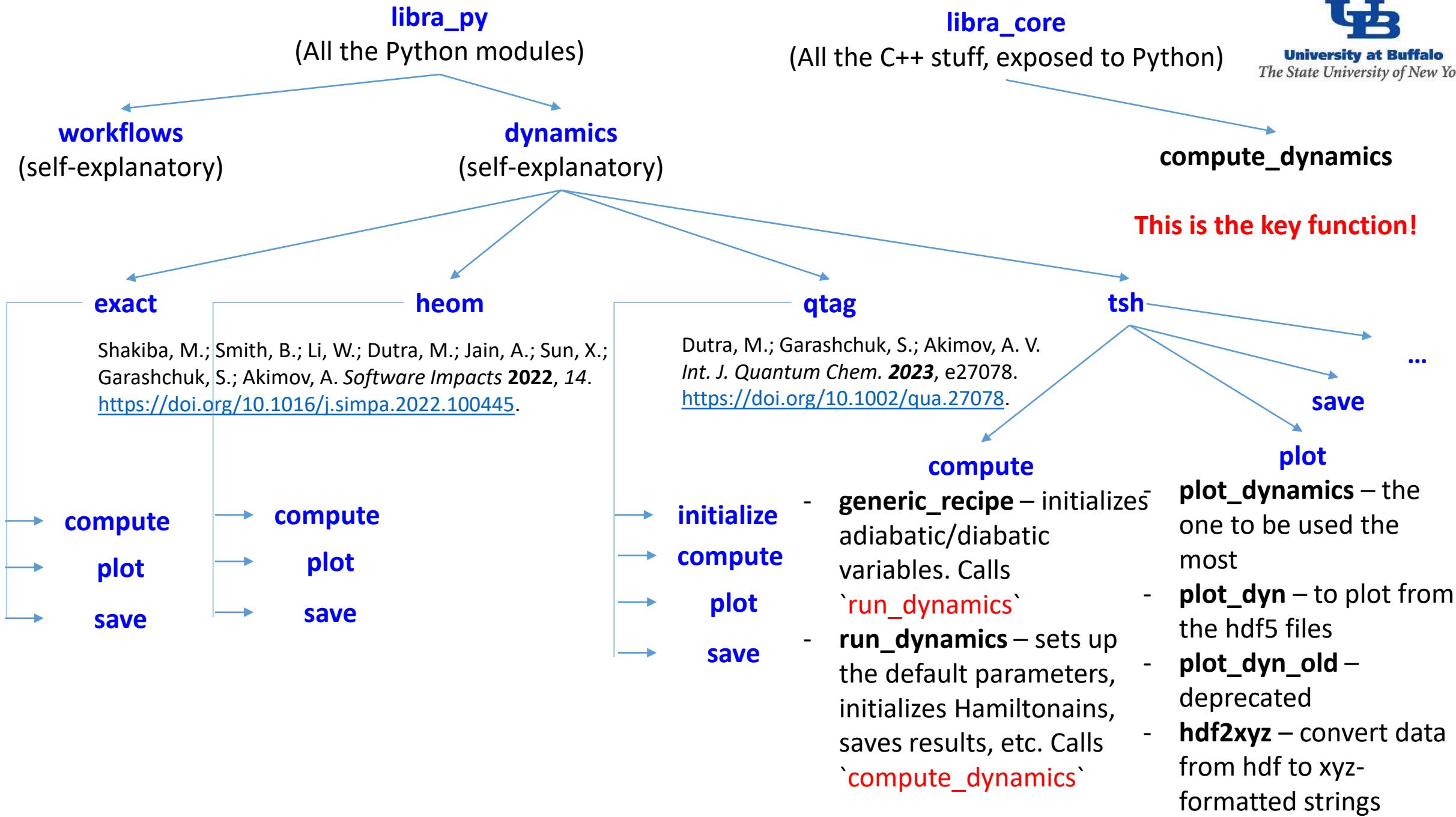
Alexey Akimov

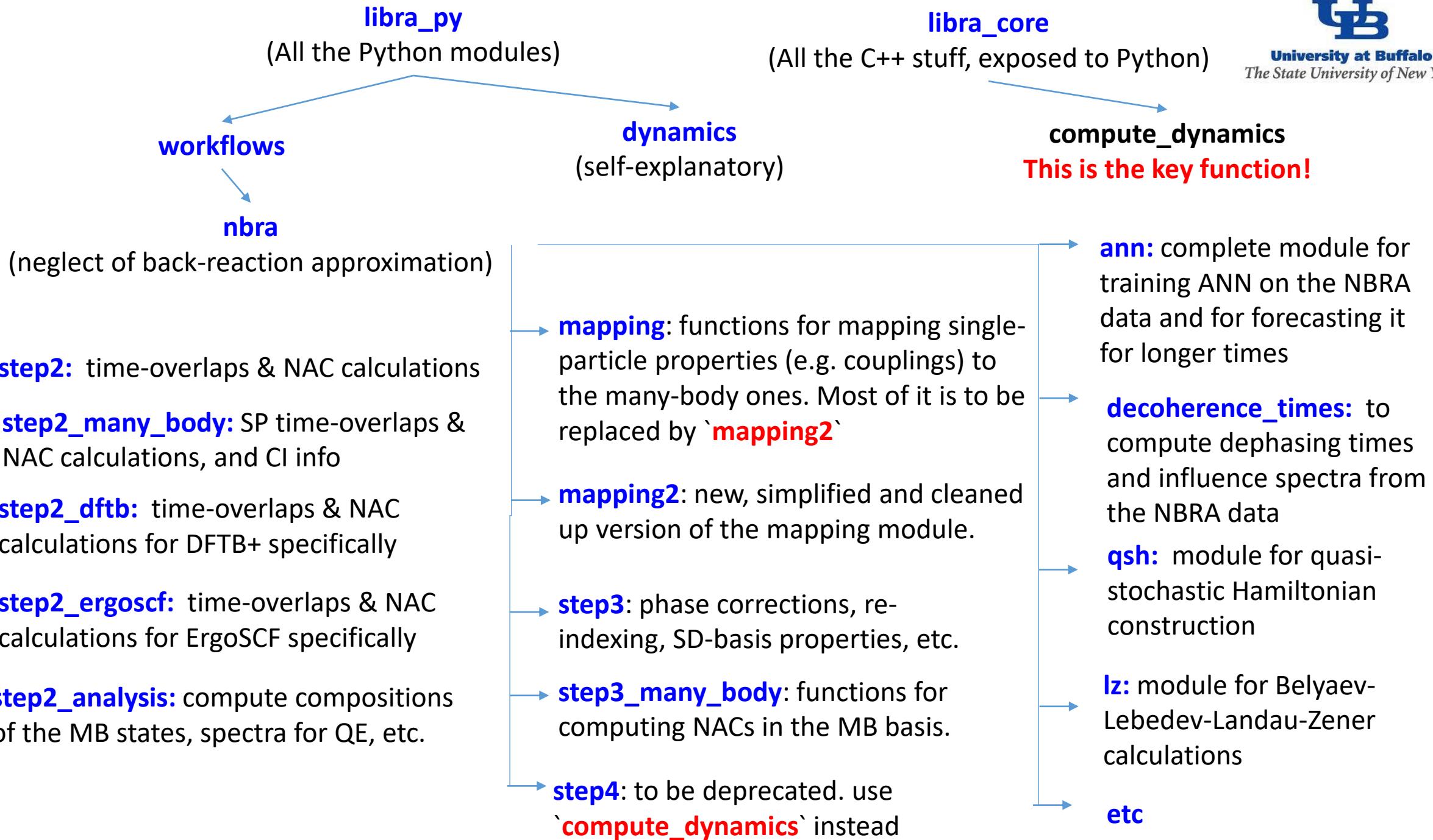
University at Buffalo, SUNY

June 13, 2023

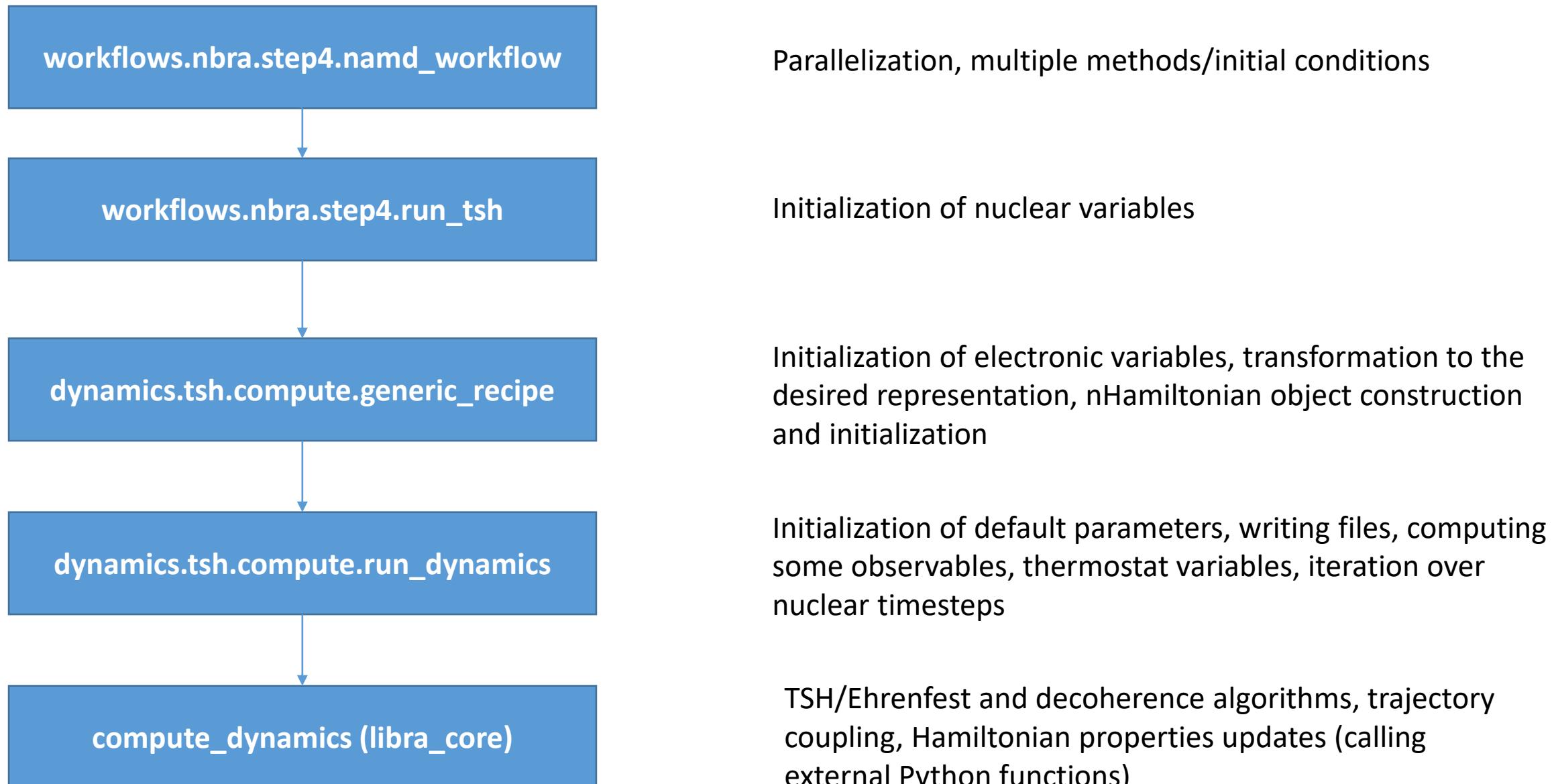
Structure of Libra package

Atomistic Workflows





Brief Overview of the Deprecated step4



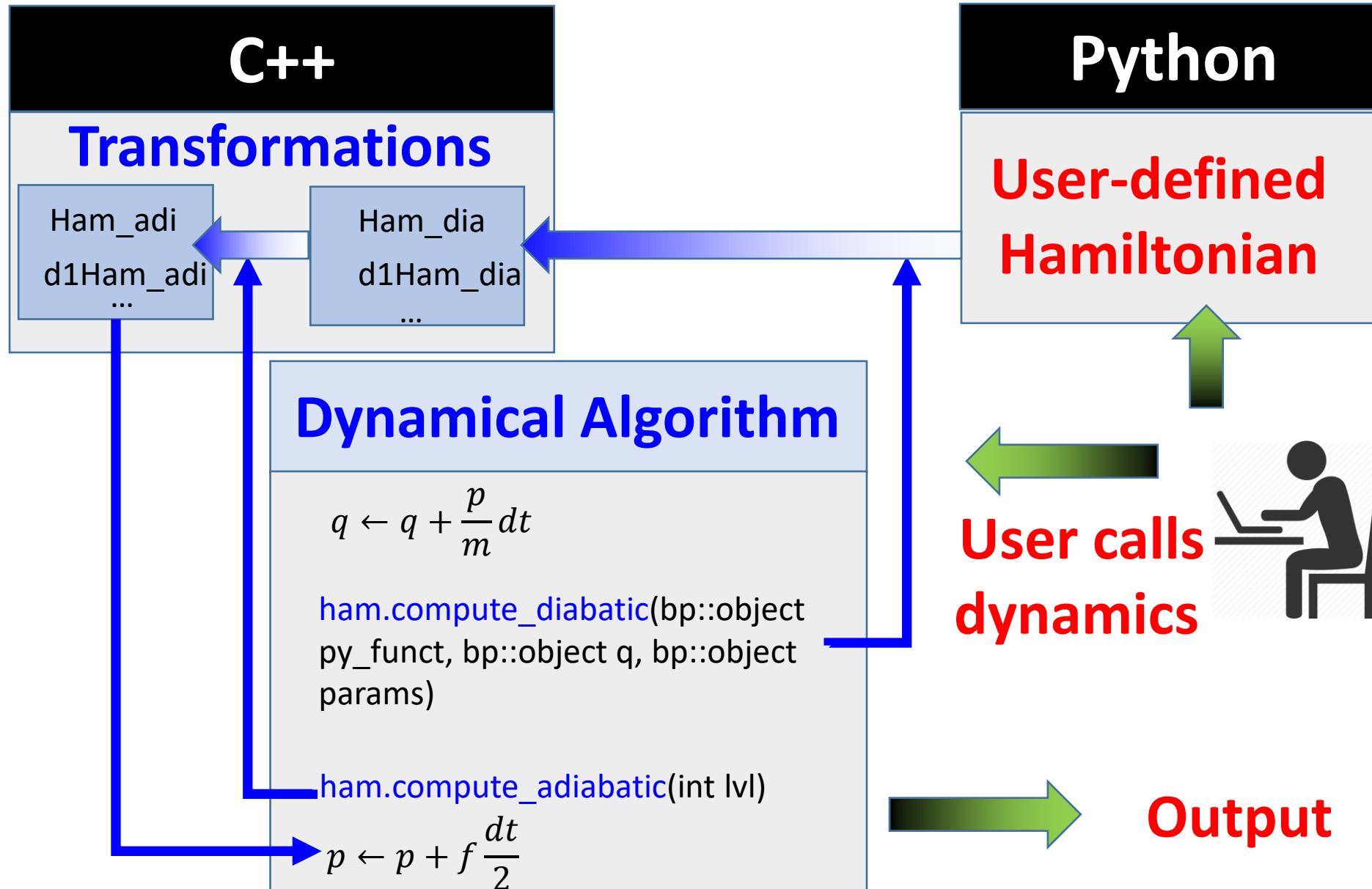
More on the n Hamiltonian class.

Making Interfaces

How `compute_dynamics` works



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Different ways of computing matrix elements.

Example of H_{dia}^{vib}

Blue = Required Input

Green = Output

Green with D = Can be set up directly via Python function call

Function	Q	P	H_{dia}	D_{dia}	d_{dia}	H_{dia}^{vib}
nHamiltonian::compute_diabatic(bp ::object py_funct ...)	D		D	D	D	D
nHamiltonian::compute_nac_dia(...)		D		D	D	
nHamiltonian::compute_hvib_dia(...)			D		D	D

Different ways of computing matrix elements.



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Example of H_{adi}^{vib}

Function	Q	P	S	H_{dia}	∇H_{dia}	D_{dia}	U	H_{adi}	∇H_{adi}	D_{adi}	d_{adi}	H_{adi}^{vib}
nHamiltonian::compute_diabatic(bp::object py_funct ...)	D		D	D	D	D						
nHamiltonian::compute_adiabatic(...)		D	D	D	D		D	D	D	D	D	D
nHamiltonian::compute_adiabatic(bp::object py_funct ...)	D						D	D	D	D	D	D
nHamiltonian::compute_nac_adi(...)		D						D	D			
nHamiltonian::compute_hvib_adi(...)						D		D	D	D	D	D

nHamiltonian class as a hierarchical data type to handle multiple trajectories

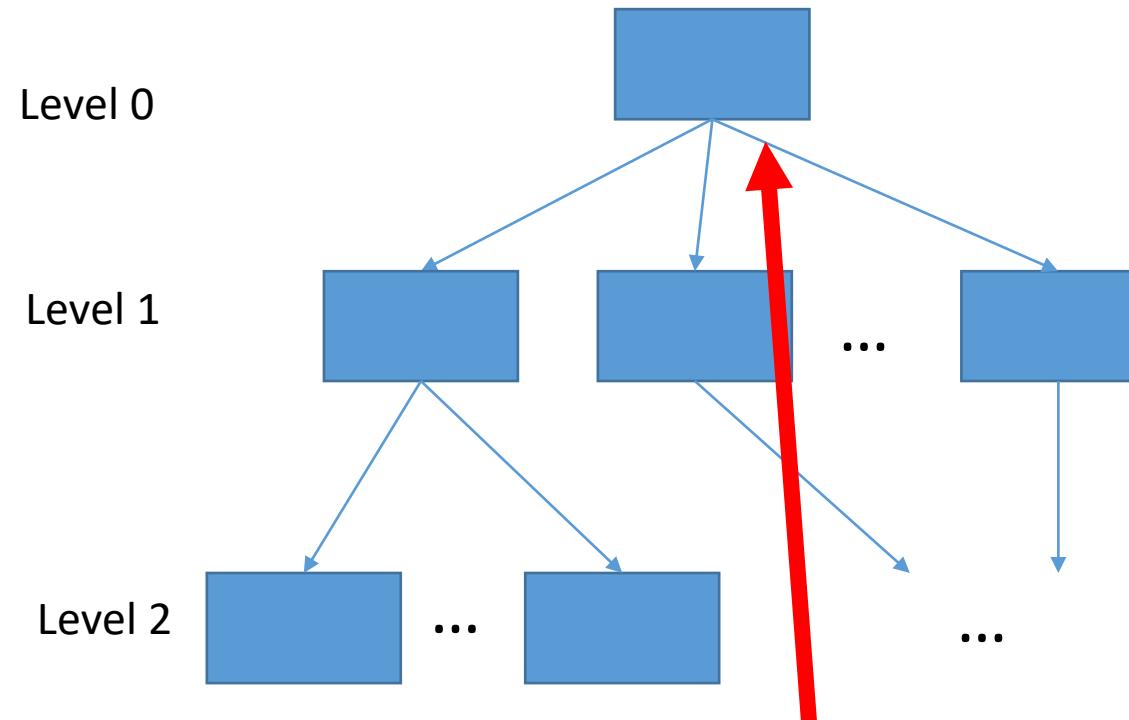
nHamiltonian

- level
- id
- nHamiltonian* parent
- vector<nHamiltonian*> children

- nnucl, nadi, ndia

- CMATRIX* ham_dia, nac_dia, hvib_dia
- CMATRIX* ham_adi, nac_adi, hvib_adi
- CMATRIX* ovlp_dia, time_overlap_dia
- CMATRIX* ovlp_adi, time_overlap_adi
- CMATRIX* basis_transform
- vector<CMATRIX*> dc1_adi, dc1_dia
- vector<CMATRIX*> d1ham_adi, d1ham_dia

- ampl_dia2adi
- ampl_adi2dia

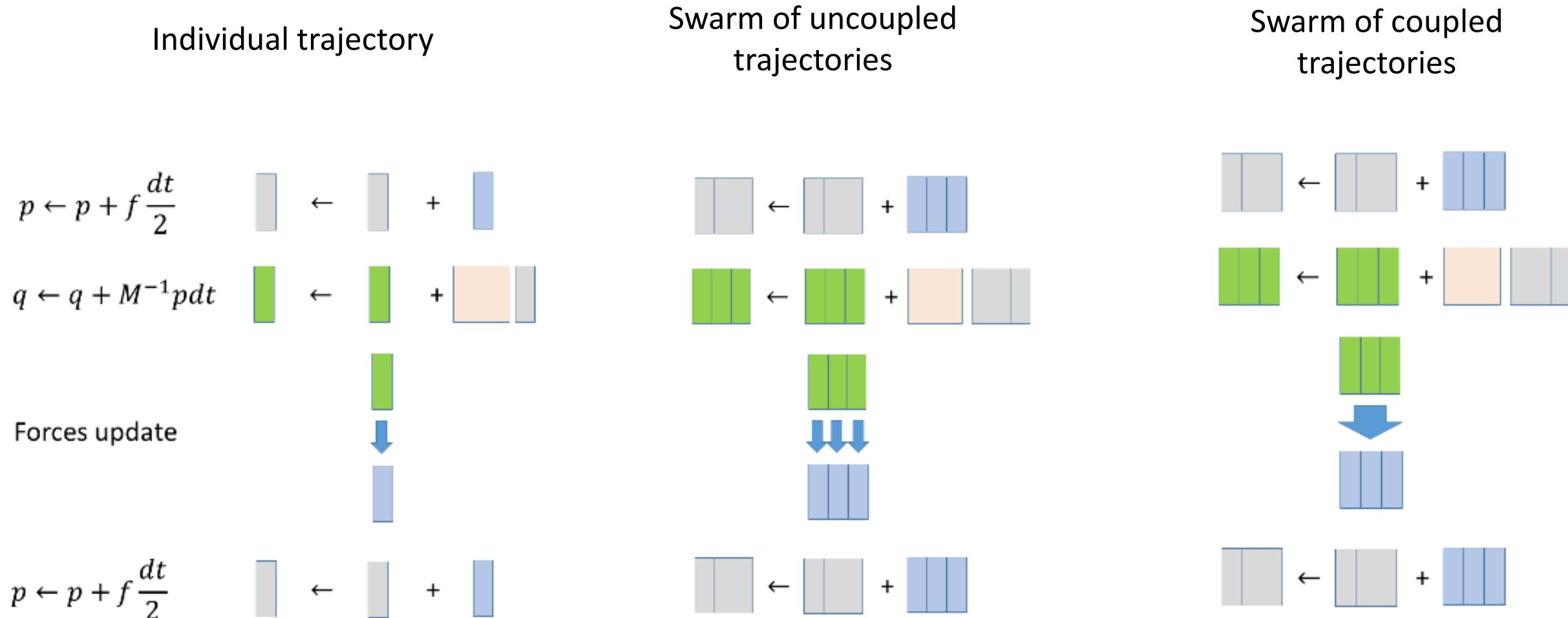


int entanglement_opt

A selector of a method to couple the trajectories in this ensemble.

- 0: no coupling [default]
- 1: ETHD
- 2: ETHD3 (experimental)
- 22: another flavor of ETHD3 (experimental)

Packing variables for multiple trajectories



Keep the Dynamical Workflow Fixed

```
for i in range(500):
    propagate_el(Cdia, Cadi, Hvib, Sdia, 0.5*dt, rep)
    p = p + 0.5*f*dt
    q = q + dt*p/m
    compute_model(model, Hdia, Sdia, d1ham_dia, dc1_dia, q, params)
    ham.compute_adiabatic(1);
    f = compute_frc(ham, Cdia, Cadi, rep)
    p = p + 0.5*f*dt
    Hvib = compute_Hvib(Hdia, Hadi, dc1_dia, dc1_adi, p, m, rep)
    propagate_el(Cdia, Cadi, Hvib, Sdia, 0.5*dt, rep)
    Etot = compute_etot(ham, p, Cdia, Cadi, m, rep)
```

User defines how to
run the dynamical simulation

User defines what function to use to compute entries in the
Hamiltonian object (diabatic/adiabatic Ham, overlap matrix, derivatives,
etc.) - NEXT

Example: Model Calculations

```
def model2(q, params):  
  
    obj = tmp()  
    obj.ham_dia = CMATRIX(2,2);  obj.ovlp_dia = CMATRIX(2,2);  
    obj.d1ham_dia = CMATRIXList(); obj.d1ham_dia.append( CMATRIX(2,2))  
    obj.dc1_dia = CMATRIXList(); obj.dc1_dia.append( CMATRIX(2,2))  
  
    x = q.get(0)  
    x0,k,D,V = params["x0"], params["k"], params["D"], params["V"]  
  
    obj.ovlp_dia.set(0,0, 1.0+0.0j); obj.ovlp_dia.set(0,1, 0.0+0.0j);  
    obj.ovlp_dia.set(1,0, 0.0+0.0j); obj.ovlp_dia.set(1,1, 1.0+0.0j);  
  
    obj.ham_dia.set(0,0, k*x*x*(1.0+0.0j) ); obj.ham_dia.set(0,1, V*(1.0+0.0j));  
    obj.ham_dia.set(1,0, V*(1.0+0.0j));      obj.ham_dia.set(1,1, (k*(x-x0)**2 + D)*(1.0+0.0j));  
  
    for i in [0]:  
        obj.d1ham_dia[i].set(0,0, 2.0*k*x*(1.0+0.0j) ); obj.d1ham_dia[i].set(0,1, 0.0+0.0j);  
        obj.d1ham_dia[i].set(1,0, 0.0+0.0j);          obj.d1ham_dia[i].set(1,1,2.0*k*(x-x0)*(1.0+0.0j));  
  
        obj.dc1_dia[i].set(0,0, 0.0+0.0j); obj.dc1_dia[i].set(0,1,-0.1+0.0j);  
        obj.dc1_dia[i].set(1,0, 0.1+0.0j); obj.dc1_dia[i].set(1,1, 0.0+0.0j);  
  
    return obj
```

Initialize Python objects

Set matrix elements according to
your model

Example: Atomistic Calculations

```
def model_atomistic(q, params, indx):  
  
    natoms = params["natoms"]; ndof = q.num_of_rows; ndia = params[ "ndia" ]  
    params[ "output_filename" ] = "detailed.out"  
  
    obj = tmp()  
    obj.ham_dia = CMATRIX(1,1);  
    obj.ovlp_dia = CMATRIX(1,1);      obj.ovlp_dia.set(0,0, 1.0+0.0j)  
    obj.d1ham_dia = CMATRIXList();  
    for i in xrange(ndof):  
        obj.d1ham_dia.append( CMATRIX(1,1) )  
  
    os.system("mkdir wd/job_"+str(indx))  
    os.system("cp dftb_in.hsd wd/job_"+str(indx) +"#"/dftb_in.hsd")  
    os.chdir("wd/job_"+str(indx))  
  
    create_input.update_coordinates(q, params)  
    os.system("srun %s < dftb_in.hsd > out" % (exe_name) ) # DFTB calculations are run here!  
    dftb_forces = parse_output.get_forces(params)  
    os.chdir("../..")  
  
    for i in xrange(ndof):  
        obj.d1ham_dia[i].set(0,0, dftb_forces[i]*(-1.0+0.0j) )  
        obj.dc1_dia[i].set(0, 0, 0.0+0.0j)  
  
    return obj
```

Initialize Python objects
Prepare and Run external program
Set matrix elements according to your model